Collection of stable bridges for constructing adaptive control
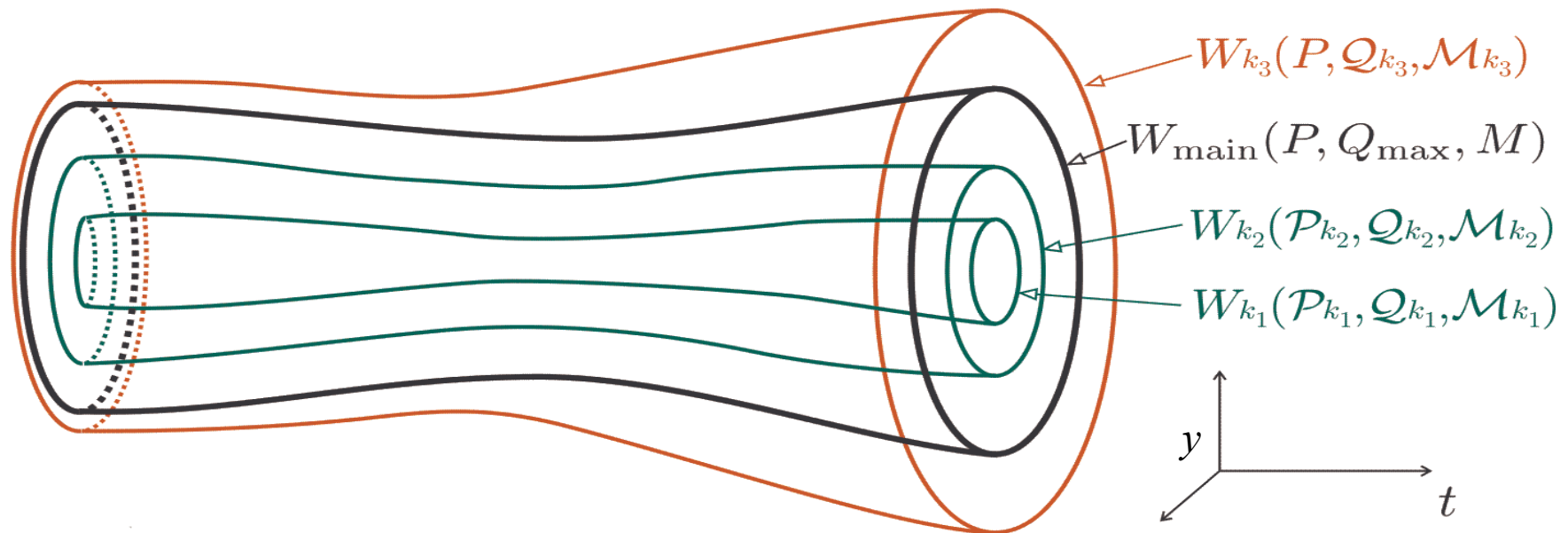
Stable bridges:

$$W_{k_1} \quad \subset \quad W_{k_2} \quad \subset \quad \ldots \quad \subset \quad W_{\text{main}} \quad \subset \quad \ldots \quad \subset \quad W_{k_3} \quad \subset \quad \ldots$$

Parameters of the bridges:

$$\mathcal{P}_{k_1} \quad \subset \quad \mathcal{P}_{k_2} \quad \subset \quad \ldots \quad \subset \quad P$$
$$\mathcal{Q}_{k_1} \quad \subset \quad \mathcal{Q}_{k_2} \quad \subset \quad \ldots \quad \subset \quad Q_{\text{max}} \quad \subset \quad \ldots \quad \subset \quad \mathcal{Q}_{k_3} \quad \subset \quad \ldots$$
$$\mathcal{M}_{k_1} \quad \subset \quad \mathcal{M}_{k_2} \quad \subset \quad \ldots \quad \subset \quad M \quad \subset \quad \ldots \quad \subset \quad \mathcal{M}_{k_3} \quad \subset \quad \ldots$$